

What is claimed is:

1. An interface device for interfacing instruments to a simulation system to  
2 enable a user to interact with the simulation system to perform a medical procedure on a  
3 simulated anatomy of a virtual patient, said interface device comprising:  
4 a peripheral in the form of a mock medical instrument capable of selective  
5 manipulation by the user;  
6 an orifice for receiving said instrument;  
7 a guide tube for directing said instrument from said orifice into said interface device;  
8 a capture mechanism for engaging said instrument to enable said interface device to  
9 measure manipulation of and provide force feedback to said instrument; and  
10 a sensing assembly to measure manipulation of and provide force feedback to said  
11 instrument, wherein said sensing assembly includes:  
12 motion detection means to measure manipulation of said captured instrument  
13 and provide signals indicating said measured manipulation to said simulation system  
14 to simulate said medical procedure; and  
15 force application means to apply force feedback to said captured instrument in  
16 response to control signals from said simulation system.
1. 2. The device of claim 1 wherein said instrument includes an endoscope.
1. 3. The device of claim 1 wherein said instrument includes a nested instrument  
2 assembly, and said interface device further includes:  
3 a plurality of capture mechanisms each engaging a corresponding instrument  
4 of said instrument assembly to enable said interface device to measure manipulation  
5 of and provide force feedback to that instrument; and  
6 a plurality of sensing assemblies each measuring manipulation of and  
7 providing force feedback to said corresponding instrument.
1. 4. The device of claim 1 wherein said interface device further includes a pivoting  
2 mechanism to pivot said orifice.

1           5. An interface device for interfacing instruments to a simulation system to  
2 enable a user to interact with the simulation system to perform a medical procedure on a  
3 simulated anatomy of a virtual patient, said interface device comprising:  
4           a plurality of peripherals in the form of mock medical instruments capable of selective  
5 manipulation by the user;  
6           a plurality of orifices for receiving said instruments;  
7           a plurality of guide tubes for directing said instruments from said orifices into said  
8 interface device;  
9           a plurality of capture mechanisms for engaging said instruments to enable said  
10 interface device to measure manipulation of and provide force feedback to said instruments;  
11 and  
12           a plurality of sensing assemblies to measure manipulation of and provide force  
13 feedback to said instruments, wherein each said sensing assembly includes:  
14            motion detection means to measure manipulation of a corresponding captured  
15 instrument and provide signals indicating said measured manipulation to said  
16 simulation system to simulate said medical procedure; and  
17            force application means to apply force feedback to said corresponding  
18 captured instrument in response to control signals from said simulation system.

1           6. The device of claim 5 wherein at least one of said instruments includes a nested  
2 instrument assembly.

1           7. In an interface device for interfacing instruments to a simulation system to  
2 enable a user to interact with the simulation system to perform a medical procedure, a capture  
3 mechanism for engaging an instrument inserted within the interface device to enable the  
4 interface device to measure manipulation of and provide force feedback to that instrument,  
5 said capture mechanism comprising:  
6            a grasping member for engaging said instrument to enable said interface device to  
7 measure manipulation of and provide force feedback to said instrument; and  
8            an actuator for activating said grasping member to engage said instrument in response  
9 to user manipulation of said instrument.

1           8.     A method for interfacing instruments to a simulation system, via an interface  
2     device, to enable a user to interact with the simulation system to perform a medical procedure  
3     on a simulated anatomy of a virtual patient, said method comprising the steps of:

4           (a) inserting a peripheral in the form of a mock medical instrument into said interface  
5     device via an orifice and guide tube, and selectively manipulating said instrument within said  
6     interface device;

7           (b) engaging said instrument, via a capture mechanism, to enable said interface  
8     device to measure manipulation of and provide force feedback to said instrument;

9           (c) measuring manipulation of said captured instrument and providing signals  
10    indicating said measured manipulation to said simulation system to simulate said medical  
11    procedure; and

12           (d) applying force feedback to said captured instrument in response to control signals  
13    from said simulation system.

1           9.     The method of claim 8 wherein said instrument includes an endoscope.

1           10.    The method of claim 8 wherein said instrument includes a nested instrument  
2     assembly, and step (b) further includes:

3           (b.1) engaging each instrument of said instrument assembly to enable said  
4     interface device to measure manipulation of and provide force feedback to that  
5     instrument;

6           step (c) further includes:

7           (c.1) measuring manipulation of said each instrument and providing signals  
8     indicating said measured manipulation to said simulation system; and

9           step (d) further includes:

10          (d.1) applying force feedback to said each instrument in response to control  
11    signals from said simulation system.

1           11.    The method of claim 8 wherein step (a) further includes:

2           (a.1) pivoting said orifice to a desired orientation.